

# DAUBECHIES FILTERS

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PREP - Wavelet Workshop, 2009



## TODAY'S SCHEDULE

- 9:00-10:15 **Lecture Five:** Cumulative Energy, Quantization, and Peak Signal-to-Noise Ratio
- 10:15-10:30 **Coffee Break** (SCA 202)
- 10:30-11:45 **Lecture Six:** Huffman Coding
- 12:00-1:00 **Lunch**
- 1:30-2:45 **Lecture Seven:** Putting it All Together: Image Compression
- 2:45-3:00 **Coffee Break** (SCA 202)
- 3:00-4:15  $\Rightarrow$  **Lecture Eight:** Daubechies Wavelet Transformations

# OUTLINE

## TODAY'S SCHEDULE

### DAUBECHIES D4 WAVELET TRANSFORMATIONS

Why Longer Filters?

Daubechies System

Solving the System

### DAUBECHIES 6-TERM FILTER

The System

### DAUBECHIES FILTERS OF EVEN LENGTH

# DAUBECHIES D4 TRANSFORMATION

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$$\sqrt{2}(0, 100 \mid 0, 0)$$

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- ▶ The Haar transform of this vector is

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- ▶ If we are looking for edges, Haar fails.

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- ▶ In this lecture we will look to build longer filters that generate orthogonal transforms.
- ▶ In addition, we want to preserve the matrix structure and its properties.
- ▶ What about a length 3 filter?

# DAUBECHIES D4 TRANSFORMATION

## WHY LONGER FILTERS?

Let's write out the top portion of a wavelet transform matrix using the filter  $(h_0, h_1, h_2)$  applied to an 6-vector:

$$H\mathbf{v} = \begin{bmatrix} h_2 & h_1 & h_0 & 0 & 0 & 0 \\ 0 & 0 & h_2 & h_1 & h_0 & 0 \\ h_0 & 0 & 0 & 0 & h_2 & h_1 \end{bmatrix} \cdot \mathbf{v}$$

There are two things to consider:

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## WHY LONGER FILTERS?

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- ▶ The downside is wrapping implicitly assumes the data are periodic.
- ▶ The other problem is the orthogonality conditions. If the rows of  $H$  are going to be orthonormal, we need:

# DAUBECHIES D4 TRANSFORMATION

## WHY LONGER FILTERS?

$$H = \begin{bmatrix} h_2 & h_1 & h_0 & 0 & 0 & 0 \\ 0 & 0 & h_2 & h_1 & h_0 & 0 \\ h_0 & 0 & 0 & 0 & h_2 & h_1 \end{bmatrix} \cdot \begin{bmatrix} h_2 & 0 & h_0 \\ h_1 & 0 & 0 \\ h_0 & h_2 & 0 \\ 0 & h_1 & 0 \\ 0 & h_0 & h_2 \\ 0 & 0 & h_1 \end{bmatrix} = I_3$$

$$h_0^2 + h_1^2 + h_2^2 = 1$$

$$h_0 h_2 = 0$$

# DAUBECHIES D4 TRANSFORMATION

## WHY LONGER FILTERS?

- ▶ The condition  $h_0 h_2 = 0$  implies either  $h_0 = 0$  or  $h_2 = 0$  so we're back to a length 2 filter!

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- ▶ It is pretty easy to verify that odd-length filters all have this problem.
- ▶ The smallest even length filter bigger than 2 is 4 - let's look at that one.

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

Let's start by writing the top half of the wavelet matrix with filter  $\mathbf{h} = (h_0, h_1, h_2, h_3)$  that we would use to process a length 8 vector:

$$H = \begin{bmatrix} h_3 & h_2 & h_1 & h_0 & 0 & 0 & 0 & 0 \\ 0 & 0 & h_3 & h_2 & h_1 & h_0 & 0 & 0 \\ 0 & 0 & 0 & 0 & h_3 & h_2 & h_1 & h_0 \\ h_1 & h_0 & 0 & 0 & 0 & 0 & h_3 & h_2 \end{bmatrix}$$

The orthogonality conditions are:

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM



$$\begin{aligned}h_0^2 + h_1^2 + h_2^2 + h_3^2 &= 1 \\h_0 h_2 + h_1 h_3 &= 0\end{aligned}$$

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- ▶ Suppose we also want  $\mathbf{h}$  to satisfy properties similar to that of the Haar transform, that is, preserve constant data and “kill” oscillatory data:

$$h_0 - h_1 + h_2 - h_3 = 0$$

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- ▶ We do get one “freebie” out of these conditions. It turns out that if these conditions are satisfied, then

$$h_0 + h_1 + h_2 + h_3 = \pm\sqrt{2}$$

(Problem 7.2, Page 243).

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

Let's pick the positive root. Then our system becomes

$$h_0^2 + h_1^2 + h_2^2 + h_3^2 = 1$$

$$h_0 h_2 + h_1 h_3 = 0$$

$$h_0 + h_1 + h_2 + h_3 = \sqrt{2}$$

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## DAUBECHIES SYSTEM

- ▶ It is straightforward to show that there is an infinite number of solutions to this system and we haven't even considered the bottom half of the matrix yet.
- ▶ If we write out the bottom half of the wavelet transform matrix, we have:

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

$$G = \begin{bmatrix} g_3 & g_2 & g_1 & g_0 & 0 & 0 & 0 & 0 \\ 0 & 0 & g_3 & g_2 & g_1 & g_0 & 0 & 0 \\ 0 & 0 & 0 & 0 & g_3 & g_2 & g_1 & g_0 \\ g_1 & g_0 & 0 & 0 & 0 & 0 & g_3 & g_2 \end{bmatrix}$$

and the orthogonality constraints for  $\mathbf{g}$  are the same as  $\mathbf{h}$ :

$$\begin{aligned} g_0^2 + g_1^2 + g_2^2 + g_3^2 &= 1 \\ g_0g_2 + g_1g_3 &= 0 \end{aligned}$$

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

Let's write out the *entire* matrix and look at conditions that must be satisfied in order for  $W_8$  to be orthogonal. We have:

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

$$W = \begin{bmatrix} h_3 & h_2 & h_1 & h_0 & 0 & 0 & 0 & 0 \\ 0 & 0 & h_3 & h_2 & h_1 & h_0 & 0 & 0 \\ 0 & 0 & 0 & 0 & h_3 & h_2 & h_1 & h_0 \\ h_1 & h_0 & 0 & 0 & 0 & 0 & h_3 & h_2 \\ \hline g_3 & g_2 & g_1 & g_0 & 0 & 0 & 0 & 0 \\ 0 & 0 & g_3 & g_2 & g_1 & g_0 & 0 & 0 \\ 0 & 0 & 0 & 0 & g_3 & g_2 & g_1 & g_0 \\ g_1 & g_0 & 0 & 0 & 0 & 0 & g_3 & g_2 \end{bmatrix}$$

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

Note that the vectors  $\mathbf{h} = (h_0, h_1, h_2, h_3)$  and  $\mathbf{g} = (h_3, -h_2, h_1, -h_0)$  are orthogonal!

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

Moreover, whenever

$$\begin{aligned}h_0^2 + h_1^2 + h_2^2 + h_3^2 &= 1 \\h_0 h_2 + h_1 h_3 &= 0\end{aligned}$$

we have

$$\begin{aligned}g_0^2 + g_1^2 + g_2^2 + g_3^2 &= h_3^2 + (-h_2)^2 + h_1^2 + (-h_0)^2 = 1 \\g_0 g_2 + g_1 g_3 &= h_3 h_1 + (-h_2)(-h_0) = 0\end{aligned}$$

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## DAUBECHIES SYSTEM

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- ▶ so the bottom half of the matrix consists of orthonormal rows.
- ▶ You can also check the other orthogonality conditions, and they all hold.

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

To summarize, if we choose  $\mathbf{h} = (h_0, h_1, h_2, h_3)$  so that

$$h_0^2 + h_1^2 + h_2^2 + h_3^2 = 1$$

$$h_0 h_2 + h_1 h_3 = 0$$

$$h_0 + h_1 + h_2 + h_3 = \sqrt{2}$$

$$h_0 - h_1 + h_2 - h_3 = 0$$

and  $\mathbf{g} = (h_3, -h_2, h_1, -h_0)$ , then the matrix  $W_N$  is orthogonal! There's just one small problem . . .

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Why not force the high pass portion of the matrix to kill linear signals?

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- ▶ The condition Ingrid Daubechies added was incredibly simple:  
Why not force the high pass portion of the matrix to kill linear signals?
- ▶ That is, add the condition

$$h_1 - 2h_2 + 3h_3 = 0$$

# DAUBECHIES LENGTH FOUR FILTER

## DAUBECHIES SYSTEM

Our system becomes

$$h_0^2 + h_1^2 + h_2^2 + h_3^2 = 1$$

$$h_0 h_2 + h_1 h_3 = 0$$

$$h_0 + h_1 + h_2 + h_3 = \sqrt{2}$$

$$h_0 - h_1 + h_2 - h_3 = 0$$

$$h_1 - 2h_2 + 3h_3 = 0$$

It turns out that there are two real solutions to this system.

# DAUBECHIES LENGTH FOUR FILTER

## SOLVING THE SYSTEM

Let's solve this system. The equation

$$h_0 h_2 + h_1 h_3 = 0$$

is equivalent to saying the vectors  $(h_0, h_1)$  and  $(h_2, h_3)$  are orthogonal. This implies that for some  $c \neq 0$ ,

$$(h_2, h_3) = c(-h_1, h_0)$$

Plugging this into  $h_0^2 + h_1^2 + h_2^2 + h_3^2 = 1$  and simplifying gives

# DAUBECHIES LENGTH FOUR FILTER

## SOLVING THE SYSTEM

$$h_0^2 + h_1^2 = \frac{1}{1 + c^2}$$

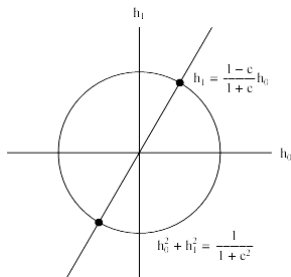
If we also plug  $(h_2, h_3) = c(-h_1, h_0)$  into  $h_0 - h_1 + h_2 - h_3 = 0$  and simplify, we have

$$h_1 = \left( \frac{1 - c}{1 + c} \right) h_0$$

# DAUBECHIES LENGTH FOUR FILTER

## SOLVING THE SYSTEM

Geometrically, we have the following graph:



# DAUBECHIES LENGTH FOUR FILTER

## SOLVING THE SYSTEM

If we plug  $(h_2, h_3) = c(-h_1, h_0)$  into

$$h_1 - 2h_2 + 3h_3 = 0$$

we obtain

$$h_1 = - \left( \frac{3c}{1 + 2c} \right) h_0$$

and this is another line through the origin. The only way we can have a solution is if the two lines through the origin have the same slope. That is,

# DAUBECHIES LENGTH FOUR FILTER

## SOLVING THE SYSTEM

$$\frac{1-c}{1+c} = -\frac{3c}{1+2c}$$

or

$$c^2 + 4c + 1 = 0$$

so that  $c = -2 \pm \sqrt{3}$ .

# DAUBECHIES LENGTH FOUR FILTER

## SOLVING THE SYSTEM

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- ▶ Can you take the positive root  $c = -2 + \sqrt{3}$  and find a solution to the system?
- ▶ To let you know if you are on the right track, you should soon arrive at  $h_1 = \sqrt{3}h_0$  and with a bit more work,

$$h_0 = \pm \frac{1 + \sqrt{3}}{4\sqrt{2}}$$

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- ▶ Take the positive value and proceed.
- ▶ OR . . . can you plug the system into Mathematica/Matlab and solve it?

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## SOLVING THE SYSTEM

The solution is

$$h_0 = \frac{1}{4\sqrt{2}} (1 + \sqrt{3}) \quad h_1 = \frac{1}{4\sqrt{2}} (3 + \sqrt{3})$$

$$h_2 = \frac{1}{4\sqrt{2}} (3 - \sqrt{3}) \quad h_3 = \frac{1}{4\sqrt{2}} (1 - \sqrt{3})$$

The solution with the negative root  $c = -2 - \sqrt{3}$  is the reflection of the above solution.

# DAUBECHIES 6-TERM FILTER

## THE SYSTEM

- ▶ If we repeat the process with  $\mathbf{h} = (h_0, \dots, h_5)$ , we arrive at the following orthogonality conditions:

$$\sum_{k=0}^5 h_k^2 = 1$$

$$h_0 h_2 + h_1 h_3 + h_2 h_4 + h_3 h_5 = 0$$

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- ▶ We have the two additional conditions:

$$h_0 + h_1 + h_2 + h_3 + h_4 + h_5 = \sqrt{2}$$

$$h_0 - h_1 + h_2 - h_3 + h_4 - h_5 = 0$$

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- ▶ This time, we need to add **two** conditions, ensuring that the high pass portion of the matrix kills linear and quadratic signals:

$$h_1 - 2h_2 + 3h_3 - 4h_4 + 5h_5 = 0$$

$$h_1 - 4h_2 + 9h_3 - 16h_4 + 25h_5 = 0$$

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- ▶ We get the following system:

# DAUBECHIES 6-TERM FILTER

## THE SYSTEM

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- ▶ Longer filters result in systems that must be solved numerically.

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- ▶ She also proved that if  $(h_0, \dots, h_L)$  is a solution, so is  $(h_L, \dots, h_0)$ .

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- ▶ She also proved that if  $(h_0, \dots, h_L)$  is a solution, so is  $(h_L, \dots, h_0)$ .
- ▶ Daubechies suggests a method for finding her so-called *extremal phase* filters.

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